WEST Search History

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DATE: Thursday, November 16, 2006

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		DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ	
☐	L15	robot and controller and display and pendant and L14	100
☐	L14	(700/245,256,247,253,249 or 345/1.2,158,161,169,2.1 or 368/680,683, or 219/121.64,121263 or 318/568.1,568.11,568.12,568.13,568.19,568.21,568.22,567,563,625,568.2 or 901/1,3,6,15,49,50).ccls.	14075
☐	L13	L12 and robot	31
☐	L12	marc.xa. and pendant.	83
☐	L11	pendant and L2	26
☐	L10	pendant and L9	16
☐	L9	display and L2	94
☐	L8	09212228.pn.	2
☐	L7	3D model and L5	10
☐	L6	model and L5	146
☐	L5	point$ and L4	313
☐	L4	display$3 and L3	403
☐	L3	pendants and controller and robot$6	615
☐	L2	"off-line programming" and robot$6	191
☐	L1	grob.in. and marc.xa.	2

END OF SEARCH HISTORY

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Search Result - Print Format

Key: IEEE JNL = IEEE Journal or Magazine, **IEE JNL** = IEE Journal or Magazine, **IEEE CNF** = IEEE Conference, **IEE CNF** = IEE Conference, **IEEE STD** = IEEE Standard

1. **Web system for control of mechatronic devices**
   Lowe, G.; Cambrell, A.;
   Control, Automation, Robotics and Vision, 2002. ICARCV 2002. 7th International Conference on
   Volume 3, 2-5 Dec. 2002 Page(s):1464 - 1469 vol.3
   IEEE CNF

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